

Regular self-proximal distances are Bregman

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Abstract

Bregman distances play a key role in generalized versions of the proximal algorithm. This paper proposes a new characterization of Bregman distances in terms of their gradient and Hessian matrix. Thanks to this characterization, we obtain two results: all the so called self-proximal distances are Bregman, and all the induced proximal distances, under some regularity assumptions, are Bregman functions.

1 Introduction

Given an open convex $C \subset \mathbb{R}^n$, we consider the optimization problem

$$f_* = \inf_{x \in \overline{C}} f(x), \quad (1)$$

where $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ is a proper, closed and convex function, and \overline{C} stands for the closure of C in \mathbb{R}^n . Auslender and Teboulle in 2006 [2] developed a complete study of the convergence of the *Interior Proximal Algorithm* (IPA), which consists of generating a sequence $(x^k)_k$ satisfying, for all $k \in \mathbb{N}$,

$$x^{k+1} \in \operatorname{Argmin}\{\lambda_k f(x) + d(x, x^k) \mid x \in \overline{C}\}, \quad k = 0, 1, 2, \dots, \quad (2)$$

Here, $(\lambda_k)_k$ is a sequence of positive reals and $d : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}_+ \cup \{+\infty\}$, with $\mathbb{R}_+ := [0, +\infty)$, is a distance-like function which is called

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a *proximal distance with respect to* C . The proximal distance d is required to have good properties, which force the iterates to stay in C , the interior of the feasible set given by \overline{C} (cf. [2, Definition 2.1] and Definition 2.1 below).

The convergence analysis of this algorithm relies on the existence of an *induced proximal distance*, that is a function H satisfying

$$\forall a, b, c \in C, \quad \langle c - b, \nabla_1 d(b, a) \rangle \leq H(c, a) - H(c, b), \quad (3)$$

where ∇_1 stands for the gradient with respect to the first variable of $d(\cdot, \cdot)$. An important class of proximal distances is the family of Bregman distances [3, 4, 5, 6, 9, 10]. The Bregman distances are *self-proximal*, that is, the previous inequality holds with $H = d$. Another popular class of proximal distances are the φ -divergence distances, and their regularized versions [1, 6, 7, 8].

Our work is motivated by the observation that in the literature, the only known self-proximal distances are Bregman distances. Therefore we investigated whether all the self-proximal distances are Bregman. To this end, we obtained a new characterization of the Bregman distances.

The paper is organized as follows. In section 2 we recall the definition of proximal distance and motivate the notions of induced proximal and self-proximal distances. Then we obtain that under assumptions of regularity, the induced proximal distance is uniquely determined by the proximal distance. Section 3 is devoted to Bregman distances; we obtain a characterization of these distances, and deduce that all self-proximal distances are Bregman. Moreover, under an assumption of suitable regularity, we prove that all the induced distances are Bregman.

2 Induced proximal distances

Given a function $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ we define the (effective) domain of f by $\text{dom } f := \{x \in \mathbb{R}^n \mid f(x) < +\infty\}$. We say that f is proper if $\text{dom } f \neq \emptyset$, and f is lower semi continuous (lsc) on \mathbb{R}^n if for all $\lambda \in \mathbb{R}$ the set $S_\lambda = \{x \in \mathbb{R}^n \mid f(x) \leq \lambda\}$ is closed. Given $\epsilon \geq 0$, an ϵ -subgradient of f at $x \in \text{dom } f$ is an element $x^* \in \mathbb{R}^n$ verifying

$$f(x') + \epsilon \geq f(x) + \langle x^*, x' - x \rangle, \quad \forall x' \in \mathbb{R}^n,$$

where $\langle \cdot, \cdot \rangle$ stands for the classical inner product of \mathbb{R}^n . The set of all ϵ -subgradients of f at x is the ϵ -subdifferential of f at x , it is denoted by $\partial_\epsilon f(x)$, with the convention that $\partial_\epsilon f(x) = \emptyset$ when $x \notin \text{dom } f$. When $\epsilon = 0$, we simply write $\partial f(x)$.

Definition 2.1 [2, Definition 2.1] A function $d : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}_+ \cup \{+\infty\}$ is called a **proximal distance** with respect to an open nonempty convex set $C \subset \mathbb{R}^n$ if for each $y \in C$ it satisfies the following properties:

- (P₁) $d(\cdot, y)$ is proper, lsc, convex on \mathbb{R}^n and C^1 on C ;
- (P₂) $\text{dom } d(\cdot, y) \subset \overline{C}$ and $\text{dom } \partial d(\cdot, y) \subset C$.
- (P₃) $d(\cdot, y)$ is level bounded in \mathbb{R}^n , i.e., $\lim_{\|u\| \rightarrow \infty} d(u, y) = +\infty$;
- (P₄) $d(y, y) = 0$.

We denote by $\mathcal{D}(C)$ the set of functions d satisfying these properties.

As we mentioned in the introduction, the IPA solves (1) by generating a sequence $(x^k)_k$ according to the iterative scheme (2), where $d \in \mathcal{D}(C)$. Due to (P₂), under suitable assumptions on f and C , the iterates generated by (2) stay in C , the interior of the constraints set \overline{C} , as the following proposition shows.

Proposition 2.1 [2, Proposition 2.1] Suppose that $f_* > -\infty$ and $\text{dom } f \cap C \neq \emptyset$, with f_* defined by (1). Let $d \in \mathcal{D}(C)$, and for all $v \in C$ consider the optimization problem

$$(P(v)) \quad f_*(v) = \inf_{u \in \overline{C}} f(u) + d(u, v).$$

Then the optimal set of $P(v)$ is nonempty and compact. For each $\epsilon \geq 0$ there exist $u(v) \in C$, $g \in \partial_\epsilon f(u(v))$ such that $g + \nabla_1 d(u(v), v) = 0$. For such $u(v) \in C$, we have $f(u(v)) + d(u(v), v) \leq f_*(v) + \epsilon$.

We now turn to the definition of the *induced proximal distance*.

Definition 2.2 We say that a function $H : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}_+ \cup \{+\infty\}$ is an **induced proximal distance** to $d \in \mathcal{D}(C)$ if it satisfies the following properties:

1. H is finite-valued on $C \times C$.
2. $\forall a \in C, H(a, a) = 0$
3. $\forall a, b, c \in C, \langle c - b, \nabla_1 d(b, a) \rangle \leq H(c, a) - H(c, b)$.

We denote by $\mathcal{F}(C)$ the set of all pairs (d, H) with $d \in \mathcal{D}(C)$ and H an induced proximal distance to d .

We say that d is **self-proximal** when $(d, d) \in \mathcal{F}(C)$, that is when

$$\forall a, b, c \in C, \quad \langle c - b, \nabla_1 d(b, a) \rangle \leq d(c, a) - d(c, b). \quad (4)$$

Let us motivate the introduction of the induced proximal distance H for the analysis of IPA. Let x^{k+1} be generated by the iterative scheme given by (2). By Proposition 2.1, there exists $g^{k+1} \in \partial f(x^{k+1})$ such that $\lambda_k g^{k+1} + \nabla_1 d(x^{k+1}, x^k) = 0$. If $(d, H) \in \mathcal{F}(C)$, we get

$$\begin{aligned} \lambda_k(f(x^{k+1}) - f(x)) &\leq \langle -\lambda_k g^{k+1}, x - x^{k+1} \rangle \\ &= \langle \nabla_1 d(x^{k+1}, x^k), x - x^{k+1} \rangle \\ &\leq H(x, x^k) - H(x, x^{k+1}), \end{aligned}$$

for all $x \in C$. Next, suppose that the inequality can be extended to every $x \in \bar{C}$. Set $S := \text{Argmin}_{\bar{C}} f$, which is supposed to be nonempty, and take any $x^* \in S$. Then $\lambda_k(f(x^{k+1}) - f(x^*)) \leq H(x^*, x^k) - H(x^*, x^{k+1})$. Since $f(x^{k+1}) \geq f^* = f(x^*)$, we deduce that

$$H(x^*, x^{k+1}) \leq H(x^*, x^k), \quad \forall x^* \in S.$$

Thus the sequence $(x^k)_k$ is H -Fejer monotone with respect to the optimal set S . This is a key property for the asymptotic convergence of $(x^k)_k$ towards an optimal solution of (1). See [2] for all details.

The previous argument motivates the introduction of the set of pairs $\mathcal{F}(\bar{C})$ defined as follows: a pair (d, H) belongs to $\mathcal{F}(\bar{C})$ if $(d, H) \in \mathcal{F}(C)$ and satisfies the following properties:

1. H is finite-valued on $\bar{C} \times C$.
2. $\forall a, b \in C, \forall c \in \bar{C}, \langle c - b, \nabla_1 d(b, a) \rangle \leq H(c, a) - H(c, b)$.
3. $\forall c \in \bar{C}$, the function $H(c, \cdot)$ is level-bounded on \mathbb{R}^n , i.e. for all $\lambda \in \mathbb{R}$, the set $\{y \in \mathbb{R}^n \mid H(c, y) \leq \lambda\}$ is bounded.

Our first result is the uniqueness of the induced proximal distance satisfying nice regularity assumptions.

Theorem 2.1 *Let $(d, H) \in \mathcal{F}(C)$. Suppose that for every $x \in C$, $H(x, \cdot)$ is C^1 on C . Then:*

(a) *If for each $y \in C$, $d(\cdot, y)$ is C^2 on C , then*

$$1. \forall x, y \in C, \nabla_2 H(x, y) = -\nabla_{1,1}^2 d(y, y)(x - y),$$

$$2. H(x, y) = \int_0^1 t \langle \nabla_{1,1}^2 d(z_t, z_t)(y - x), y - x \rangle dt,$$

where $z_t = x + t(y - x)$.

(b) *If for each $x \in C$, $\nabla_1 d(x, \cdot)$ is C^1 on C , then*

$$3. \forall x, y \in C, \nabla_2 H(x, y) = \nabla_{1,2}^2 d(y, y)(x - y),$$

$$4. H(x, y) = -\int_0^1 t \langle \nabla_{1,2}^2 d(z_t, z_t)(y - x), y - x \rangle dt,$$

where $z_t = x + t(y - x)$.

Thus, under any of the above assumptions on d , there exists a unique induced proximal distance H to d such that for all $x \in C$, $H(x, \cdot)$ is C^1 on C .

Proof. We prove (a). We suppose that for all $y \in C$, $d(\cdot, y)$ is C^2 on C and for all $x \in C$, $H(x, \cdot)$ is C^1 on C . Let $x, y \in C$, and define $\Phi : C \rightarrow \mathbb{R}$ by $\Phi(z) := H(x, y) - H(x, z) - \langle x - z, \nabla_1 d(z, y) \rangle$. Since H is an induced proximal distance to d , for all $z \in C$, we have $\Phi(z) \geq 0$. Since $d(\cdot, y) \geq 0$ on C and $d(y, y) = 0$, we have $\nabla_1 d(y, y) = 0$. This yields $\Phi(y) = 0$, then y minimizes Φ on C . We deduce that $\nabla \Phi(y) = 0$ (because C is an open set), and computing this gradient, we have, for all $x, y \in C$, $\nabla_2 H(x, y) = -\nabla_{1,1}^2 d(y, y)(x - y)$. Let $x, y \in C$. Since $H(x, x) = 0$, we have:

$$\begin{aligned} H(x, y) &= \int_0^1 \langle \nabla_2 H(x, x + t(y - x)), y - x \rangle dt \\ &= - \int_0^1 \langle \nabla_{1,1}^2 d(z_t, z_t)(x - z_t), y - x \rangle dt \\ &= \int_0^1 t \langle \nabla_{1,1}^2 d(z_t, z_t)(y - x), y - x \rangle dt, \end{aligned}$$

where $z_t = x + t(y - x)$. Therefore H is uniquely determined by d , so there exists a unique proximal distance H to d such that for all $x \in C$, $H(x, \cdot)$ is C^1 on C . We have thus proven items 1. and 2.; items 3. and 4. are obtained by similar arguments. \square

As a direct consequence of Theorem 2.1, we get the following necessary conditions on the proximal distance d to have that the corresponding induced proximal distance is given by the Euclidean norm, an interesting special case for practical computations.

Corollary 2.1 *Let $d \in \mathcal{D}(C)$ be a proximal distance such that there exists a real $\eta > 0$ satisfying $(d, (x, y) \rightarrow \eta\|y - x\|^2) \in \mathcal{F}(C)$, that is*

$$\forall a, b, c \in C, \langle c - b, \nabla_1 d(b, a) \rangle \leq \eta(\|c - a\|^2 - \|c - b\|^2). \quad (5)$$

The following assertions hold:

- (a) if for all $y \in C$, $d(\cdot, y)$ is C^2 on C , then $\nabla_{1,1}^2 d(y, y) = 2\eta I$,
- (b) if for all $x \in C$, $\nabla_1 d(x, \cdot)$ is C^1 on C , then $\nabla_{1,2}^2 d(y, y) = -2\eta I$.

The notation I stands for the identity matrix on \mathbb{R}^n .

3 Bregman distances

Let us recall the definition of Bregman distance.

Definition 3.1 Let $h : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be proper, lsc and convex on \mathbb{R}^n , with $\text{dom } h \subset \bar{C}$ and $\text{dom } \nabla h = C$. Suppose that h is strictly convex and continuous on $\text{dom } h$, and C^1 on $\text{int}(\text{dom } h) = C$. Set

$$\begin{aligned} D_h(x, y) &:= h(x) - h(y) - \langle \nabla h(y), x - y \rangle, \quad x \in \mathbb{R}^n, \quad y \in C \\ &:= +\infty \quad \text{otherwise.} \end{aligned} \quad (6)$$

The function D_h is the **Bregman distance** with kernel h .

It is easy to see that if the kernel h is level bounded, then the corresponding D_h is a proximal distance in the sense of Definition 2.1.

Remark 3.1 Every Bregman distance D_h satisfies the following property, which is referred to as the three point identity (see [5]): $\forall a, b \in C, \forall c \in \text{dom } h$

$$D_h(c, a) = D_h(c, b) + D_h(b, a) + \langle \nabla_1 D_h(b, a), c - b \rangle. \quad (7)$$

It is straightforward that (7) implies (4) with $d = D_h$, so that every Bregman distance is self-proximal. We will show that under fairly general conditions, self-proximal distances are indeed Bregman distances. To this end, we introduce new characterizations of Bregman functions.

Remark 3.2 When h is C^2 on C , then $\nabla_{1,1}^2 D_h(x, y) = \nabla^2 h(x)$ and $\nabla_2 D_h(x, y) = -\nabla^2 h(y)(x - y)$, therefore D_h enjoys the following property:

$$\forall x, y \in C, \quad \nabla_2 D_h(x, y) = -\nabla_{1,1}^2 D_h(y, y)(x - y). \quad (8)$$

Thus (8) is a necessary condition for a proximal distance to be Bregman. An interesting question is to know whether this is also sufficient for a proximal distance to be a Bregman distance.

Remark 3.3 If $d = D_h$ is a Bregman distance, and $\tilde{h} : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ is a convex function, then $D_h = D_{\tilde{h}}$ if and only if $\text{dom } h = \text{dom } \tilde{h}$ and $h - \tilde{h}$ is an affine function on $\text{dom } h$. Therefore, we can easily establish that for all arbitrary $y_0 \in C$, the function $\tilde{h}(x) := d(x, y_0)$ verifies the following properties: $\text{dom } \tilde{h} = \text{dom } h$ and $h - \tilde{h}$ is an affine function on $\text{dom } h$. Thus we have $d = D_{d(\cdot, y_0)}$. Moreover, h is strictly convex if and only if there exists an element $y \in C$ such that $d(\cdot, y)$ is strictly convex.

Since the three point identity (7) is stronger than inequality (4), we first verify that every proximal distance satisfying the three point identity is indeed Bregman.

Proposition 3.1 *Let $d \in \mathcal{D}(C)$ be a proximal distance satisfying the three point identity, that is,*

$$\forall a, b \in C, \forall c \in \mathbb{R}^n, \quad d(c, a) = d(c, b) + d(b, a) + \langle c - b, \nabla_1 d(b, a) \rangle. \quad (9)$$

Then there exists a function $h : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ lsc, proper and convex on \mathbb{R}^n , C^1 on C , with $\text{dom } \nabla h = C$, $C \subset \text{dom } h \subset \overline{C}$ and for all $(x, y) \in \mathbb{R}^n \times C$, $d(x, y) = D_h(x, y)$.

Proof. Let $y_0 \in C$ and $h : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ be defined by $h(x) := d(x, y_0)$. Since d is a proximal distance, the function h is lsc, proper and convex on \mathbb{R}^n , C^1 on C with $\text{dom } \nabla h = C$ and $C \subset \text{dom } h \subset \overline{C}$. Let $x \in \mathbb{R}^n$ and $y \in C$. Applying the equality (9), we obtain

$$d(x, y_0) = d(x, y) + d(y, y_0) + \langle x - y, \nabla_1 d(y, y_0) \rangle,$$

which implies that

$$h(x) = d(x, y) + h(y) + \langle x - y, \nabla h(y) \rangle.$$

Therefore, for all $x \in \mathbb{R}^n$ and $y \in C$, we have $d(x, y) = D_h(x, y)$. \square

The following theorem gives us a necessary and sufficient condition for a function defined on $C \times C$ to be written as a Bregman distance.

Theorem 3.1 *Let a function $F : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}_+ \cup \{+\infty\}$ be such that $C \times C \subset \text{dom } F$ and for all $x \in C$, $F(x, x) = 0$. We suppose that F is C^1 on $C \times C$, and for all $y \in C$, $F(\cdot, y)$ is C^2 on C . Then there exists a function $h : C \rightarrow \mathbb{R}$ convex and C^2 on C , satisfying*

$$\begin{aligned} \forall x, y \in C, \quad F(x, y) &= h(x) - [h(y) + \langle \nabla h(y), x - y \rangle] \\ &= D_h(x, y), \end{aligned} \quad (10)$$

if and only if

$$\forall x, y \in C, \quad \nabla_2 F(x, y) = -\nabla_{1,1}^2 F(y, y)(x - y), \quad (11)$$

and in this case, for any $y_0 \in C$, the function $h : C \rightarrow \mathbb{R}$ defined by $h(x) = F(x, y_0)$ satisfies the equality (10).

Additionally, if for all $y \in C$, $F(\cdot, y)$ is finite-valued and continuous on \overline{C} , then any C^1 function $h : C \rightarrow \mathbb{R}$ satisfying the equality (10) can be extended in a continuous function \bar{h} on \overline{C} , so that the equality (10) holds with \bar{h} for all $(x, y) \in \overline{C} \times C$.

Remark 3.4 The equality (10) mixed with the convexity of h on C tells us that $F(\cdot, y)$ must be convex for all $y \in C$, so the above theorem shows us that the first assumptions about F (namely $F(\cdot, \cdot) \geq 0$ on $C \times C$ and $F(x, x) = 0$ for all $x \in C$) mixed with the assumption (11) imply that $F(\cdot, y)$ is convex on C for all $y \in C$.

Remark 3.5 The second part of the theorem shows that if for all $y \in C$, the function $F(\cdot, y)$ is finite-valued and continuous on \bar{C} , then (11) implies the equality $F = D_{\bar{h}}$ on $\bar{C} \times C$ with \bar{h} a function which is C^1 on C and continuous on \bar{C} . That implies the continuity of F on $\bar{C} \times C$.

Proof of Theorem 3.1. From (8), equality (10) implies equality (11).

We now prove the converse, more precisely we prove that equality (11) implies that $F = D_{F(\cdot, y_0)}$ on $C \times C$ for any arbitrary $y_0 \in C$. We suppose that (11) holds. Let $y_1, y_2 \in C$. We show that the function $F(\cdot, y_2) - F(\cdot, y_1)$ is an affine function on C : $\forall x \in C$,

$$\begin{aligned} F(x, y_2) - F(x, y_1) &= \int_0^1 \langle \nabla_2 F(x, y_1 + t(y_2 - y_1)), y_2 - y_1 \rangle dt \\ &= - \int_0^1 \langle \nabla_{1,1}^2 F(y_t, y_t)(x - y_t), y_2 - y_1 \rangle dt \text{ by (11)} \\ &= - \int_0^1 \langle x - y_t, \nabla_{1,1}^2 F(y_t, y_t)(y_2 - y_1) \rangle dt, \end{aligned} \tag{12}$$

because the Hessian matrix $\nabla_{1,1}^2 F(y_t, y_t)$ is a symmetric matrix with $y_t := y_1 + t(y_2 - y_1)$. The last expression is an affine function with respect to x , therefore, since the Hessian matrix of an affine function is equal to zero, we deduce that

$$\forall x, y_1, y_2 \in C, \quad \nabla_{1,1}^2 F(x, y_1) = \nabla_{1,1}^2 F(x, y_2). \tag{13}$$

We choose an element $y_0 \in C$ and define $h : C \rightarrow \mathbb{R}$ by

$$\forall x \in C, \quad h(x) := F(x, y_0). \tag{14}$$

By assumption, h is C^2 on C . We now define $H : C \times C \rightarrow \mathbb{R}$ by

$$\begin{aligned} \forall x, y \in C \quad H(x, y) &:= h(x) - [h(y) + \langle \nabla h(y), x - y \rangle] \\ &= D_h(x, y). \end{aligned} \tag{15}$$

We will show that $F = H$ on $C \times C$. Actually, we will show that $\nabla F = \nabla H$ on $C \times C$. We first compute ∇H :

$$\nabla_1 H(x, y) = \nabla h(x) - \nabla h(y), \quad \nabla_2 H(x, y) = -\nabla^2 h(y)(x - y). \tag{16}$$

We now compute $\nabla F(x, y)$. For $y \in C$ and $t \in [0, 1]$, we set $y_t := y_0 + t(y - y_0)$, and obtain

$$\begin{aligned}
\forall x, y \in C, F(x, y) &= F(x, y_0) - \int_0^1 \langle x - y_t, \nabla_{1,1}^2 F(y_t, y_t)(y - y_0) \rangle dt \text{ by (12)} \\
&= h(x) - \int_0^1 \langle x, \nabla_{1,1}^2 F(y_t, y_t)(y - y_0) \rangle dt \\
&\quad + \int_0^1 \langle y_t, \nabla_{1,1}^2 F(y_t, y_t)(y - y_0) \rangle dt \\
&= h(x) - \left\langle x, \int_0^1 \nabla_{1,1}^2 F(y_t, y_t)(y - y_0) dt \right\rangle \\
&\quad + \int_0^1 \langle y_t, \nabla_{1,1}^2 F(y_t, y_t)(y - y_0) \rangle dt
\end{aligned}$$

with $\int_0^1 \nabla_{1,1}^2 F(y_t, y_t)(y - y_0) dt$ a vectorial integral, that is an integral component by component. Therefore we obtain:

$$\begin{aligned}
\forall x, y \in C, \nabla_1 F(x, y) &= \nabla h(x) - \int_0^1 \nabla_{1,1}^2 F(y_t, y_t)(y - y_0) dt \\
&= \nabla h(x) - \int_0^1 \nabla_{1,1}^2 F(y_t, y_0)(y - y_0) dt \text{ by (13)} \\
&= \nabla h(x) - (\nabla_1 F(y, y_0) - \nabla_1 F(y_0, y_0)) \\
&= \nabla h(x) - \nabla h(y).
\end{aligned} \tag{17}$$

In the last line we use the equality $\nabla_1 F(y_0, y_0) = 0$ (this is due to $F(\cdot, y_0) \geq 0$ on C and $F(y_0, y_0) = 0$, so y_0 is a minimizer of $F(\cdot, y_0)$ on the open set C).

We now compute $\nabla_2 F(x, y)$:

$$\begin{aligned}
\forall x, y \in C, \nabla_2 F(x, y) &= -\nabla_{1,1}^2 F(y, y)(x - y) \text{ by (11)} \\
&= -\nabla_{1,1}^2 F(y, y_0)(x - y) \text{ by (13)} \\
&= -\nabla^2 h(y)(x - y).
\end{aligned} \tag{18}$$

From the equalities (16), (17) and (18), we deduce that $\nabla F = \nabla H$ on $C \times C$, thus $F = H + c$ on $C \times C$, with c being a constant. Since $F(x, x) = H(x, x) = 0$, for all $x \in C$, we deduce that $c = 0$, then $F = H$ on $C \times C$. We conclude that for all $(x, y) \in C \times C$, $F(x, y) = h(x) - h(y) - \langle \nabla h(y), x - y \rangle$.

By the non-negativity of F , we have $h(x) \geq h(y) + \langle \nabla h(y), x - y \rangle$, for all $(x, y) \in C$, which implies the convexity of h on C .

We suppose that for all $y \in C$, $F(\cdot, y)$ is finite-valued and continuous on \bar{C} . Consider a C^1 function $h : C \rightarrow \mathbb{R}$ such that $F = D_h$ on $C \times C$.

We choose an element $y_1 \in C$ and define $\tilde{F} := F(\cdot, y_1)$. By assumption \tilde{F} is finite-valued and continuous on \overline{C} . An easy computation gives:

$$\begin{aligned}\tilde{F}(x) &= F(x, y_1) \\ &= D_h(x, y_1) \\ &= h(x) - h(y_1) - \langle \nabla h(y_1), x - y_1 \rangle.\end{aligned}$$

Therefore $\tilde{F} - h = -[h(y_1) + \langle \nabla h(y_1), \cdot - y_1 \rangle]$ is an affine function on C , \tilde{F} is continuous on \overline{C} , so we deduce that h can be extended in a continuous function on \overline{C} . Denoting by \bar{h} its continuous extension on \overline{C} , we obtain that $D_{\bar{h}}$ is continuous on $\overline{C} \times C$.

Let $(x, y) \in \overline{C} \times C$. Since $F(\cdot, y) = D_{\bar{h}}(\cdot, y)$ on C and both functions are continuous on \overline{C} , we deduce that $F(\cdot, y) = D_{\bar{h}}(\cdot, y)$ on \overline{C} , thus $F(x, y) = D_{\bar{h}}(x, y)$. \square

From this theorem we deduce a characterization of Bregman distances.

Proposition 3.2 *Let $d \in \mathcal{D}(C)$. We suppose that d is C^1 on $C \times C$, and for all $y \in C$, $d(\cdot, y)$ is C^2 on C . Then there exists a function $h : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ lsc, proper and convex on \mathbb{R}^n , C^2 on C , with $\text{dom } \nabla h = C$, $\text{dom } h \subset \overline{C}$ and*

$$\begin{aligned}\forall x, y \in C \quad d(x, y) &= h(x) - [h(y) + \langle \nabla h(y), x - y \rangle] \\ &= D_h(x, y),\end{aligned}\tag{19}$$

if and only if

$$\forall x, y \in C, \quad \nabla_2 d(x, y) = -\nabla_{1,1}^2 d(y, y)(x - y).\tag{20}$$

In this case, if for all $y \in C$, $d(\cdot, y)$ is finite-valued and continuous on \overline{C} , then any function $h : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ lsc, proper and convex on \mathbb{R}^n , C^1 on C , with $\text{dom } \nabla h = C$, $\text{dom } h \subset \overline{C}$ and $d = D_h$ on $C \times C$ satisfies the following items:

1. $\text{dom } h = \overline{C}$ and h is continuous on \overline{C} .
2. $\forall x \in \mathbb{R}^n, \forall y \in C, d(x, y) = h(x) - h(y) - \langle \nabla h(y), x - y \rangle$.

Moreover, if there exists an element $y \in C$ such that $d(\cdot, y)$ is strictly convex on \overline{C} , then h is also strictly convex on \overline{C} .

Remark 3.6 *In the second part of the proposition, the strict convexity and the continuity of h on its domain mixed with the equality $d = D_h$ on $\mathbb{R}^n \times C$ ensure that d is a Bregman distance in the sense of Definition 3.1. Similar to Theorem 3.1, Proposition 3.2 shows that under assumption (20), if for all $y \in C$, $d(\cdot, y)$ is finite-valued and continuous on \overline{C} , then d is continuous on $\overline{C} \times C$.*

Proof of Proposition 3.2. Suppose that the equality (20) holds. Take an element $y_0 \in C$ and define $h : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ by $h(x) = d(x, y_0)$. By Theorem 3.1 we have $d = D_h$ on $C \times C$. By definition of a proximal distance, the function h is lsc, proper and convex on \mathbb{R}^n , $\text{dom } \nabla h = C$ and $\text{dom } h \subset \overline{C}$. Moreover h is C^2 on C by assumption on d .

Suppose that for all $y \in C$, $d(\cdot, y)$ is finite-valued and continuous on \overline{C} . Consider an arbitrary function $h : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ lsc and convex on \mathbb{R}^n , C^1 on C with $\text{dom } \nabla h = C$, $\text{dom } h \subset \overline{C}$ and $d = D_h$ on $C \times C$. Let $(\bar{x}, y) \in \overline{C} \times C$. Since $d(\cdot, y)$ is continuous on \overline{C} and h is lsc on \mathbb{R}^n , we have:

$$\begin{aligned} d(\bar{x}, y) &= \lim_{x \xrightarrow{C} \bar{x}} d(x, y) \\ &= \lim_{x \xrightarrow{C} \bar{x}} D_h(x, y) \\ &= \lim_{x \xrightarrow{C} \bar{x}} h(x) - [h(y) + \langle \nabla h(y), x - y \rangle] \\ &\geq h(\bar{x}) - [h(y) + \langle \nabla h(y), \bar{x} - y \rangle]. \end{aligned}$$

This inequality implies that $h(\bar{x}) < +\infty$, moreover \bar{x} is an arbitrary element of \overline{C} , so h is finite-valued on \overline{C} . By assumption $\text{dom } h \subset \overline{C}$, then $\text{dom } h = \overline{C}$. We now prove that $d(\bar{x}, y) \leq h(\bar{x}) - [h(y) + \langle \nabla h(y), \bar{x} - y \rangle]$. Take an arbitrary element $x \in C$, since h is convex we have

$$\forall t \in (0, 1), \quad h((1-t)\bar{x} + tx) \leq (1-t)h(\bar{x}) + th(x). \quad (21)$$

Since C is a nonempty open convex set, $x \in C$ and $\bar{x} \in \overline{C}$, we have, for all $t \in (0, 1)$, $(1-t)\bar{x} + tx \in C$. This implies that

$$d((1-t)\bar{x} + tx, y) = D_h((1-t)\bar{x} + tx, y),$$

thus

$$h((1-t)\bar{x} + tx) = d((1-t)\bar{x} + tx, y) + h(y) + \langle \nabla h(y), (1-t)\bar{x} + tx - y \rangle. \quad (22)$$

Finally, combining (21) with (22), we obtain, for all $t \in (0, 1)$,

$$d((1-t)\bar{x} + tx, y) + h(y) + \langle \nabla h(y), (1-t)\bar{x} + tx - y \rangle \leq (1-t)h(\bar{x}) + th(x).$$

Letting t tend to zero and using the continuity of $d(\cdot, y)$ at \bar{x} , we deduce that

$$d(\bar{x}, y) \leq h(\bar{x}) - [h(y) + \langle \nabla h(y), \bar{x} - y \rangle],$$

which proves that $d(\bar{x}, y) = h(\bar{x}) - [h(y) + \langle \nabla h(y), \bar{x} - y \rangle]$. We have proven that $d = D_h$ on $\bar{C} \times C$.

Let $x \in \mathbb{R}^n \setminus \bar{C}$ and $y \in C$. By definition of a proximal distance we have $d(x, y) = +\infty$, since $\text{dom } h = \bar{C}$ we have $h(x) = +\infty$, so $D_h(x, y) = +\infty = d(x, y)$.

The continuity of h on \bar{C} results from the equality, for an arbitrary $y_0 \in C$, $d(\cdot, y_0) = D_h(\cdot, y_0) = h - [h(y_0) + \langle \nabla h(y_0), \cdot - y_0 \rangle]$ on \bar{C} . Since $d(\cdot, y_0)$ is continuous on \bar{C} , h is also continuous on \bar{C} .

We now suppose that there exists an element $y_1 \in C$ such that $d(\cdot, y_1)$ is strictly convex on \bar{C} . Since $d(x, y_1) = h(x) - [h(y_1) + \langle \nabla h(y_1), x - y_1 \rangle]$ for all $(x, y) \in \bar{C} \times C$, the function $h - d(\cdot, y_1)$ is an affine function on \bar{C} , thus the function h is strictly convex on \bar{C} because $d(\cdot, y_1)$ is strictly convex on \bar{C} . \square

The following corollary shows that the unique self-proximal distances satisfying a regularity assumption are the Bregman distances.

Corollary 3.1 *Let $d \in \mathcal{D}(C)$ be a self-proximal distance, that is d satisfies the inequality (4). Moreover, we suppose that d is C^1 on $C \times C$, and for all $y \in C$, $d(\cdot, y)$ is C^2 on C . Then there exists a function $h : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ lsc, proper and convex on \mathbb{R}^n , C^2 on C , with $\text{dom } \nabla h = C$, $\text{dom } h \subset \bar{C}$ and*

$$\begin{aligned} \forall x, y \in C, \quad d(x, y) &= h(x) - [h(y) + \langle \nabla h(y), x - y \rangle] \\ &= D_h(x, y). \end{aligned} \quad (23)$$

Additionally, if for all $y \in C$, $d(\cdot, y)$ is finite-valued and continuous on \bar{C} , then any function $h : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ lsc, proper and convex on \mathbb{R}^n , C^1 on C , with $\text{dom } \nabla h = C$, $\text{dom } h \subset \bar{C}$ and $d = D_h$ on $C \times C$ satisfies the following items:

1. $\text{dom } h = \bar{C}$ and h is continuous on \bar{C} .
2. $\forall x \in \mathbb{R}^n, \forall y \in C, d(x, y) = h(x) - h(y) - \langle \nabla h(y), x - y \rangle$.

Moreover, if there exists an element $y \in C$ such that $d(\cdot, y)$ is strictly convex on \bar{C} , then h is also strictly convex on \bar{C} .

Proof of Corollary 3.1. Applying Theorem 2.1 with $H = d$, we have

$$\forall x, y \in C, \quad \nabla_2 d(x, y) = -\nabla_{1,1}^2 d(y, y)(x - y).$$

Therefore, Corollary 3.1 is a direct consequence of Proposition 3.2. \square

It is important to remark that the assumptions of regularity for the function d in the above theorems are stronger than in the definition

of a proximal distance. However, the actual functions that are used in practice typically enjoy some regularity. The following theorem shows that under a stronger assumption of regularity on d and H , for any $(d, H) \in \mathcal{F}(C)$, H is a Bregman function on C .

Theorem 3.2 *Let $(d, H) \in \mathcal{F}(C)$. Suppose that d is C^4 on $C \times C$, and for all $x \in C$, $H(x, \cdot)$ is C^1 on C . Then there exists a function $h : C \rightarrow \mathbb{R}$ convex and C^2 on C , with*

$$\begin{aligned} \forall x, y \in C, \quad H(x, y) &= h(x) - [h(y) + \langle \nabla h(y), x - y \rangle] \\ &= D_h(x, y). \end{aligned} \quad (24)$$

Additionally, if for all $y \in C$, $H(\cdot, y)$ is finite-valued and continuous on \overline{C} , then any C^1 function $h : C \rightarrow \mathbb{R}$ satisfying the equality (24) can be extended in a continuous function \bar{h} on \overline{C} , so that the equality (24) holds with \bar{h} for all $(x, y) \in \overline{C} \times C$.

Remark 3.7 *We observe that according to Theorem 3.2, if d is C^4 on $C \times C$ and for all $x \in C$, $H(x, \cdot)$ is C^1 on C , then for all $y \in C$, $H(\cdot, y)$ is convex on C , while the convexity of $H(\cdot, y)$ was not needed in the definition of the induced proximal distance.*

Proof of Theorem 3.2. From Theorem 2.1 we have, for all $x, y \in C$,

$$\nabla_2 H(x, y) = -\nabla_{1,1}^2 d(y, y)(x - y). \quad (25)$$

In order to apply Theorem 3.1, we show that for all $y \in C$,

$$\nabla_{1,1}^2 d(y, y) = \nabla_{1,1}^2 H(y, y).$$

We start with the following equality, proven in Proposition 2.1:

$$H(x, y) = \int_0^1 t \langle \nabla_{1,1}^2 d(x + t(y - x), x + t(y - x))(y - x), y - x \rangle dt.$$

Let $y \in C$, and define $G_y : C \times [0, 1] \rightarrow \mathbb{R}$ by

$$G_y(x, t) = t \langle \nabla_{1,1}^2 d(x + t(y - x), x + t(y - x))(y - x), y - x \rangle.$$

We see that

$$H(x, y) = \int_0^1 G_y(x, t) dt.$$

Since d is C^4 on $C \times C$, the function G_y is C^2 on $C \times [0, 1]$, and $[0, 1]$ is a compact set, therefore, by theorem of derivation of a parametric integral, $H(\cdot, y)$ is C^2 on C and we have

$$\nabla_{1,1}^2 H(x, y) = \int_0^1 \nabla_{1,1}^2 G_y(x, t) dt,$$

this integral of matrix is component by component.

We need now to compute the quantity $\nabla_{1,1}^2 G_y(y, t)$. Define the function $F_y : C \times [0, 1] \rightarrow \mathbb{R}^n$ by

$$F_y(x, t) = \nabla_{1,1}^2 d(x + t(y - x), x + t(y - x))(x - y).$$

Since we have $G_y(x, t) = t\langle F_y(x, t), x - y \rangle$, we deduce that

$$\nabla_1 G_y(x, t) = tD_1 F_y(x, t)(x - y) + tF_y(x, t).$$

Therefore we have

$$\nabla_{1,1}^2 G_y(x, t) = tD_{1,1}^2 F_y(x, t)(x - y) + 2tD_1 F_y(x, t).$$

Then $\nabla_{1,1}^2 G_y(y, t) = 2tD_1 F_y(y, t)$. The last step consists of computing $D_1 F_y(y, t)$. We fix an arbitrary $t \in [0, 1]$. By continuity, we have

$$\lim_{x \rightarrow y} \nabla_{1,1}^2 d(x + t(y - x), x + t(y - x)) = \nabla_{1,1}^2 d(y, y),$$

thus, there exists a real $r > 0$ and a function $\varepsilon_{t,y} : B(0, r) \rightarrow \mathbb{R}^{n \times n}$ satisfying, for all $x \in B(y, r)$,

$$\nabla_{1,1}^2 d(x + t(y - x), x + t(y - x)) = \nabla_{1,1}^2 d(y, y) + \varepsilon_{t,y}(x - y)$$

with $\varepsilon_{t,y}(s) \rightarrow 0$ whenever $\|s\| \rightarrow 0$. It ensues that

$$\begin{aligned} F_y(x, t) &= (\nabla_{1,1}^2 d(y, y) + \varepsilon_{t,y}(x - y))(x - y) \\ &= \nabla_{1,1}^2 d(y, y)(x - y) + \varepsilon_{t,y}(x - y)(x - y) \\ &= F_y(y, t) + \nabla_{1,1}^2 d(y, y)(x - y) + \varepsilon_{t,y}(x - y)(x - y) \text{ since } F_y(y, t) = 0. \end{aligned}$$

Therefore $D_1 F_y(y, t) = \nabla_{1,1}^2 d(y, y)$ then $\nabla_{1,1}^2 G_y(y, t) = 2t\nabla_{1,1}^2 d(y, y)$, which gives

$$\begin{aligned} \nabla_{1,1}^2 H(y, y) &= \int_0^1 \nabla_{1,1}^2 G_y(y, t) dt \\ &= \int_0^1 2t\nabla_{1,1}^2 d(y, y) dt = \nabla_{1,1}^2 d(y, y). \end{aligned}$$

This and (25) tell us that $\forall x, y \in C$, $\nabla_2 H(x, y) = -\nabla_{1,1}^2 H(y, y)(x - y)$. Thus we can conclude by Theorem 3.1. Indeed, by Theorem 3.1, there exists a function $h : C \rightarrow \mathbb{R}$ convex and C^2 on C , with

$$\begin{aligned} \forall x, y \in C \quad d(x, y) &= h(x) - [h(y) + \langle \nabla h(y), x - y \rangle] \\ &:= D_h(x, y). \end{aligned}$$

Still by Theorem 3.1, if $\overline{C} \times C \subset \text{dom } H$ and $H(\cdot, y)$ is continuous on \overline{C} for all $y \in C$, then there exists a continuous extension of h satisfying the equality on $\overline{C} \times C$. \square

It is worth noticing that Corollary 3.1 is not a consequence of Theorem 3.2, because Theorem 3.2 needs the function to be C^4 , while Corollary 3.1 only needs d to be C^2 .

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